

Group number: DEC1705

Project title: Drone Energy Delivery

Client &/Advisor: Geiger/Chen

Team Members &/Role: Dustin Reed: Communication Justin Howe: Team Lead, Jeffery Schons: Webmaster, Chidike Ubani: Key Concept Holder, Eric Himmelblau, Avanish Kuntla

o **Weekly Summary**

We finished the navigation of the control app, and started focusing on integrating the precise landing capabilities, which will be executed through a combination of OpenCV and a PID controller, into the app.

o **Past week accomplishments**

- Dustin Reed: Finished waypoint capabilities of the app, did testing of code, did live test of waypoint missions with drone, ordered and received circuit parts
- Avanish Kuntla: Worked through tutorial of joystick input, live tested waypoint missions of drone, researched how to run C/C++ code in android studio
- Jeffery Schons: worked on getting cpp opencv code to work on android
- Justin Howe: Created the PID controller that we will use for final guidance on landing. It will receive the coordinate information from the OpenCV implementation and will then give a valid control input for the drone to correct its course and position.
- Chidike Ubani: Finished OpenCV C++ code
- Eric Himmelblau: Spent time learning the android version of OpenCV

o **Individual contributions**

<u>NAME</u>	<u>Individual Contributions</u>	<u>Hours this week</u>	<u>HOURS cumulative</u>
Dustin Reed	Finished waypoint capabilities of the app, did testing of code, did live test of waypoint missions with drone, ordered and received circuit parts	8	60
Avanish Kuntla	Worked through tutorial of joystick input, live tested waypoint missions of drone,	7	54

	researched how to run C/C++ code in android studio		
Jeffery Schons	worked on getting cpp opencv code to work on android	7	41
Chidike Ubani	Finished OpenCV C++ implementation.	4	43
Justin Howe	Created and initially tested PID controller for X any Y on landing	5	58
Eric Himmelblau	Spent time learning the android version of OpenCV	4	34

○ **Comments and extended discussion**

We are coming into the home stretch. All of our parts for the app are pretty much done, the only task left is integrating all of the individual parts into a single app, getting them to play nice with each other, and do final testing.

○ **Plan for coming week**

- Dustin Reed: Receive modular parts of code, integrate into the main app, test the main app. Get a function to take photos with camera, and work on assembling the charger.
- Avani Kuntla: Work on creating a charger prototype, code gimbal usage, improve waypoint mission capabilities
- Jeffery Schons: fully integrate the opencv into app, get app working with photos from the camera,
- Chidike Ubani: Integrate OpenCV with the app
- Justin Howe: Integrate PID with the OpenCV implementation into the app

○ **Summary of weekly advisor meeting**

Our advisors were unable to attend a meeting this week.